

Centre de Robotique

Localisation for Mobile Mapping Systems, Experimental results and analysis on rural and urban environments

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FCOLE DES MINES DE PARIS

Presentation Schema

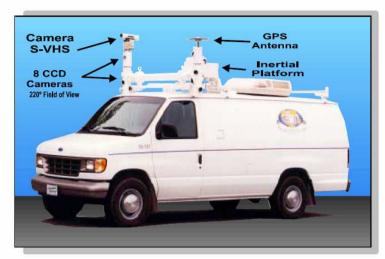
Introduction - Context

Experimental Data and Analysis

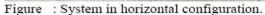
Proposed Improvement by Post-Processing

Conclusion

Examples of Mobile Mapping Systems (MMS)







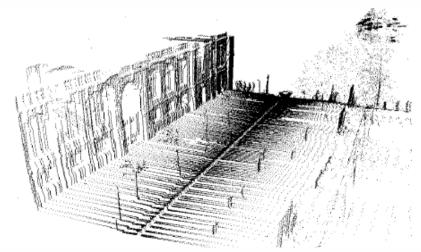




LARA - 3D



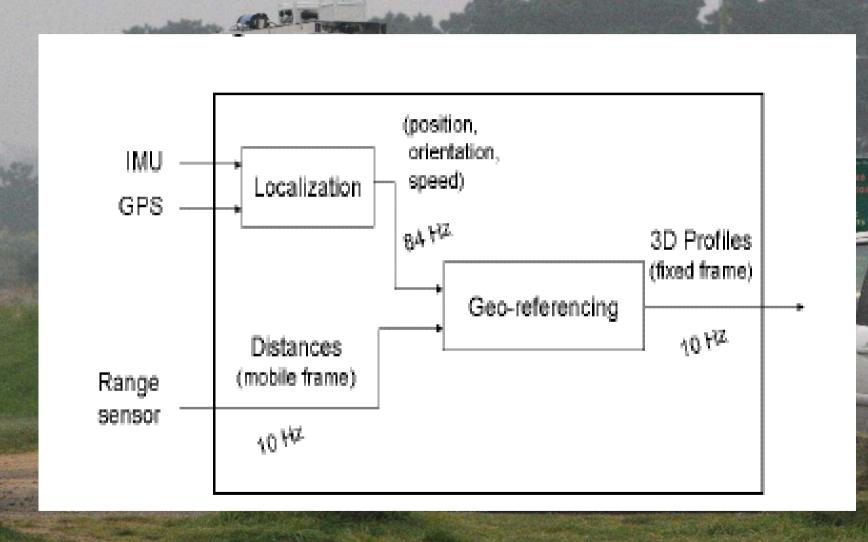




LARA-3D Sensors



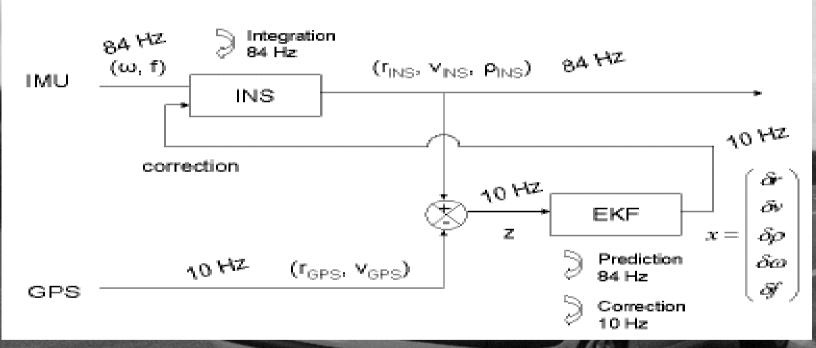
LARA-3D System Architecture





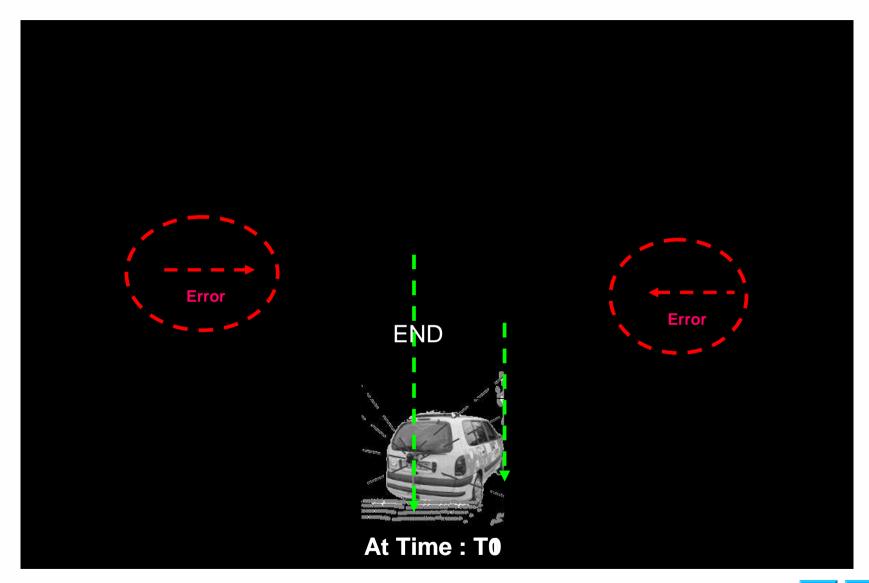
LARA-3D Position Orientation System (POS) Functionality







Why localisation is important in MMS?







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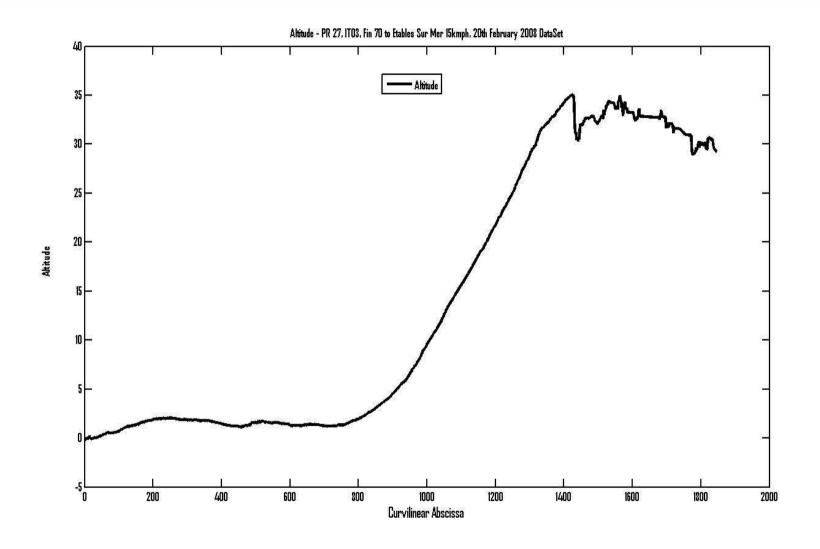
Conclusion

LARA 3D - Generation of 3D Maps

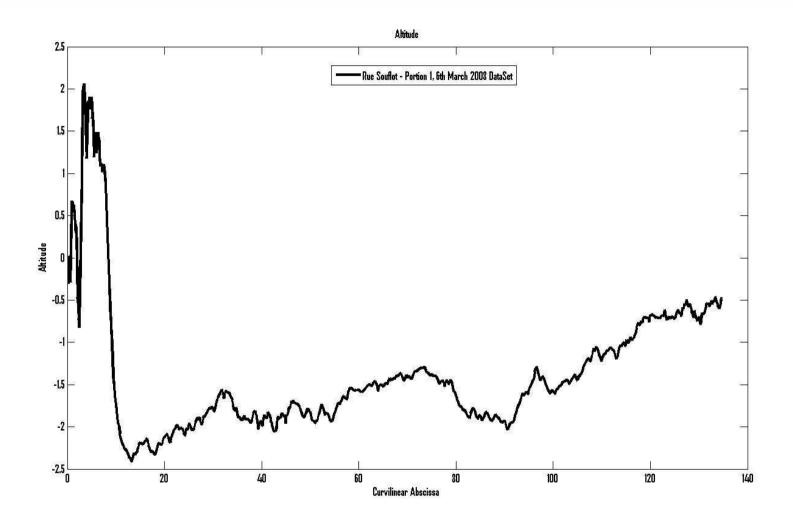








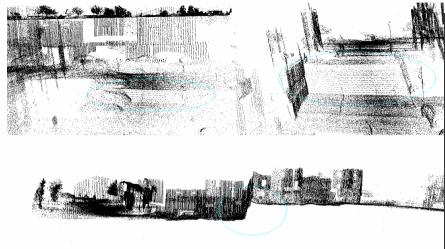




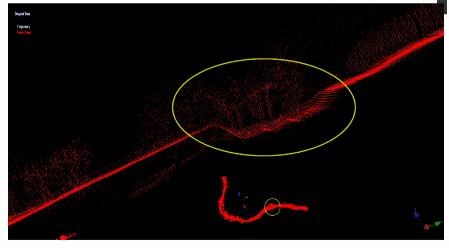


Two problems identified – Jump in Altitude









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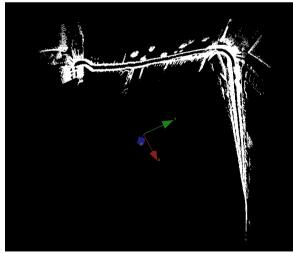
Two problems identified – Yaw problems













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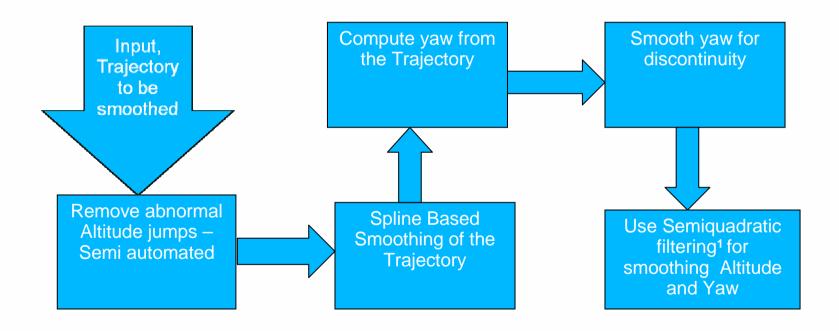
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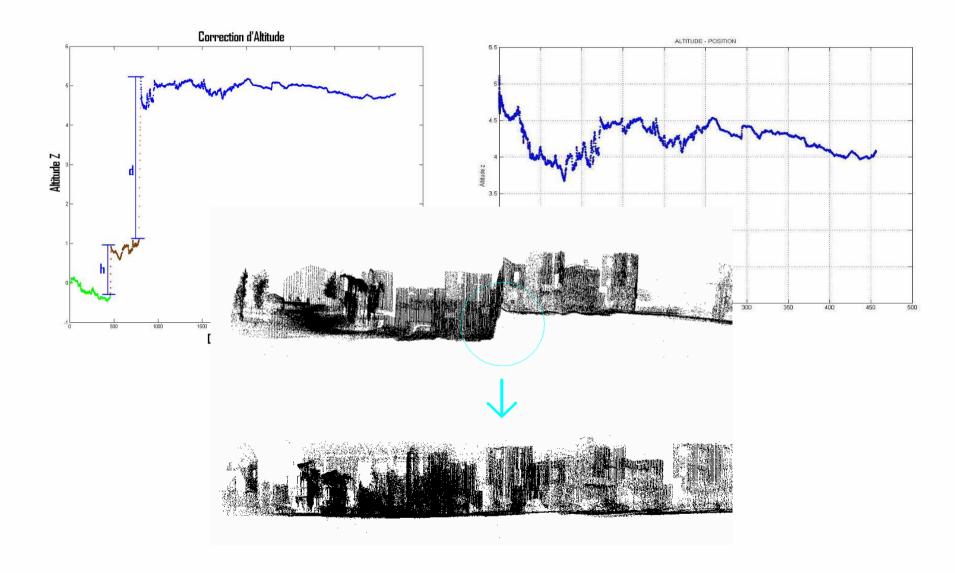
Post Processing Technique used and results

Present Steps Involved in the Process

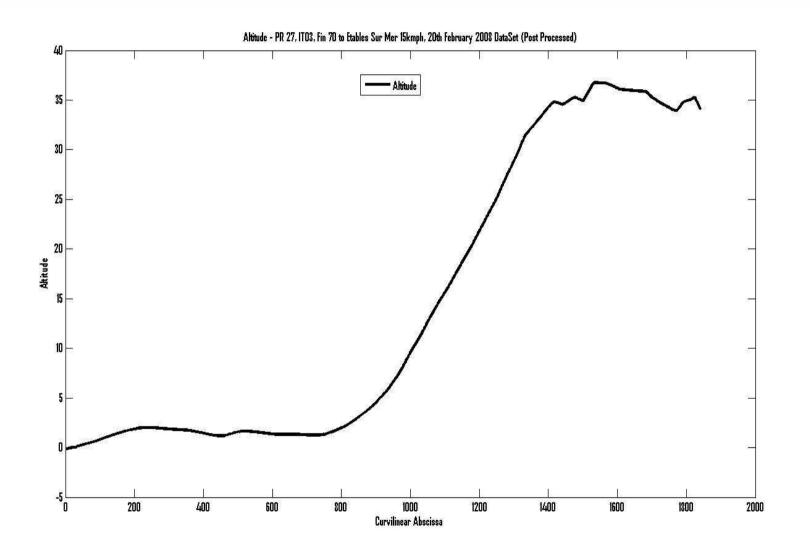


1. Implimentation based on the work from LRPC Strassbourg, P. Charbonnier, J. Tarel, S. leng. (2006)

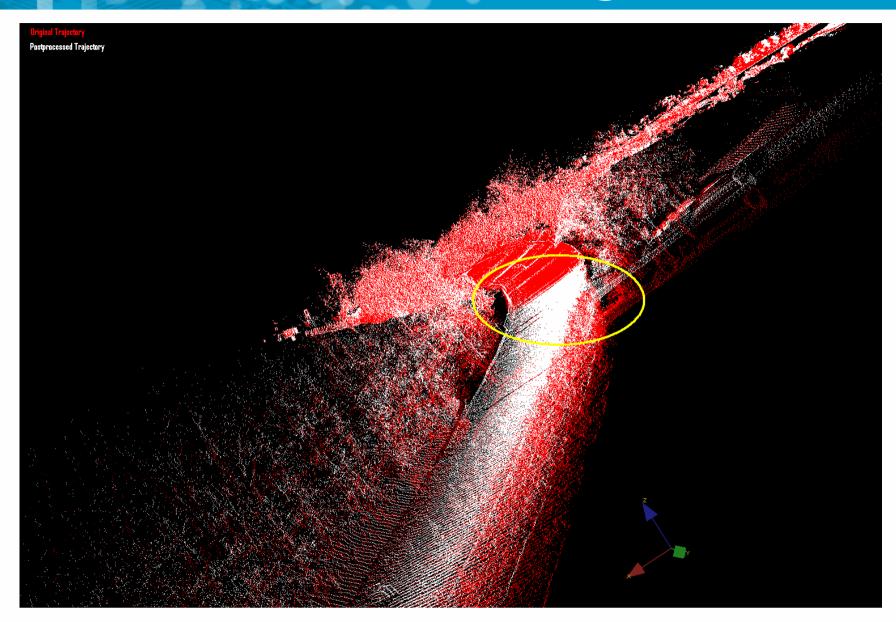




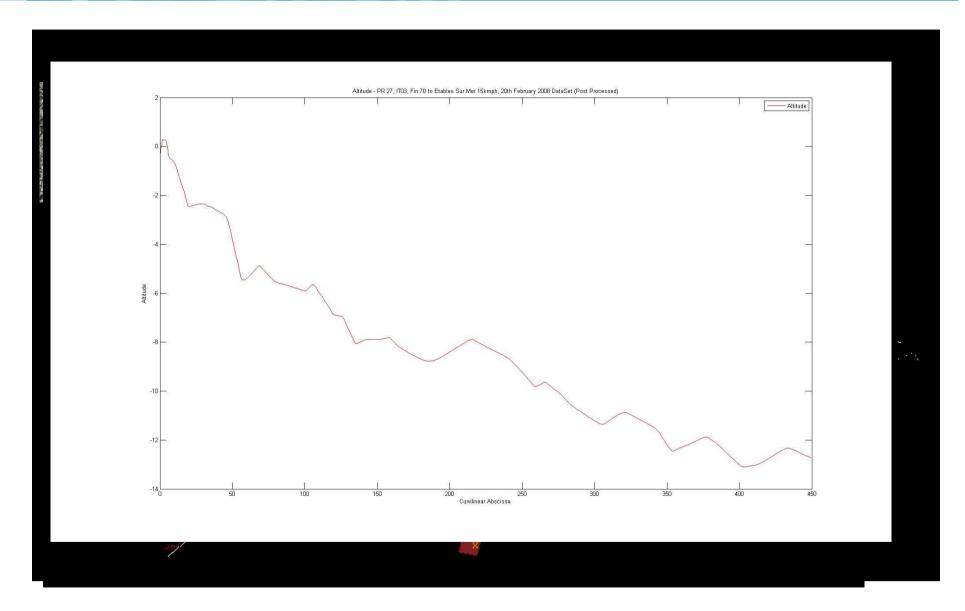




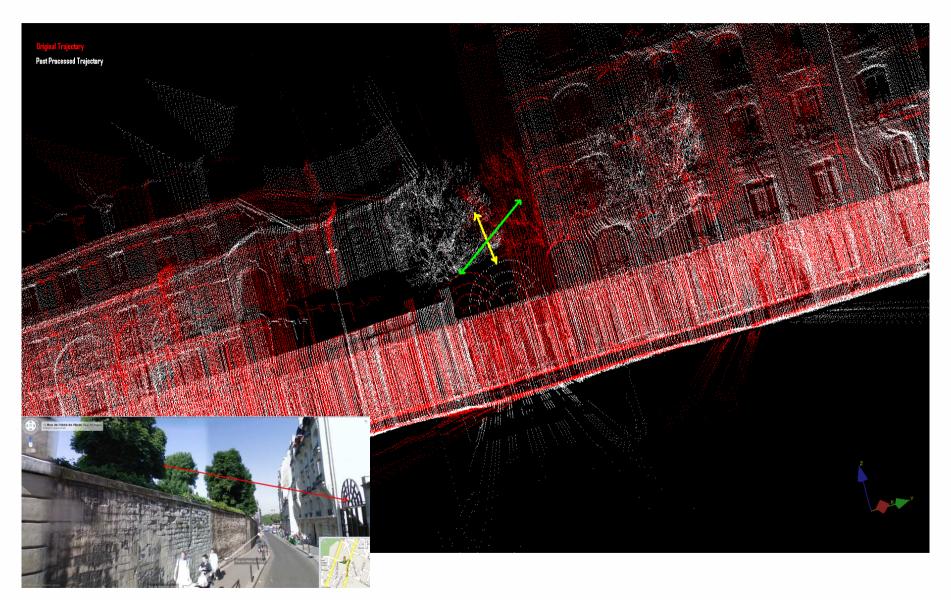












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Choice of Post Processing Approach – Quicker and direct way of achieving the objective of getting a nicer 3D maps/images.

We could even work with the data which are collected and processed long time ago to achieve better results.

In the long-term we will modify the EKF to have similar results as with the post processing techniques.

But at the end, this could also lead us to use both the modified EKF and the post processing techniques in order to obtain better results.

Questions



Thank You for Listening