GT5 Interactions personnes/ systèmes robotiques

Rachid ALAMI & Mohamed CHETOUANI Rachid.Alami@laas.fr

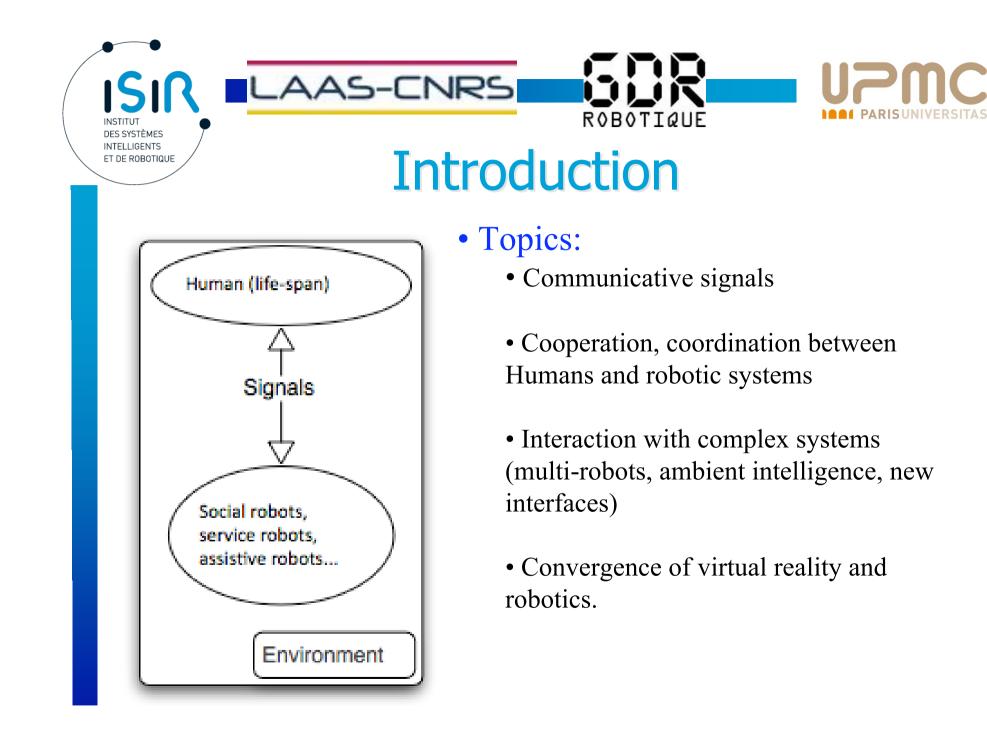


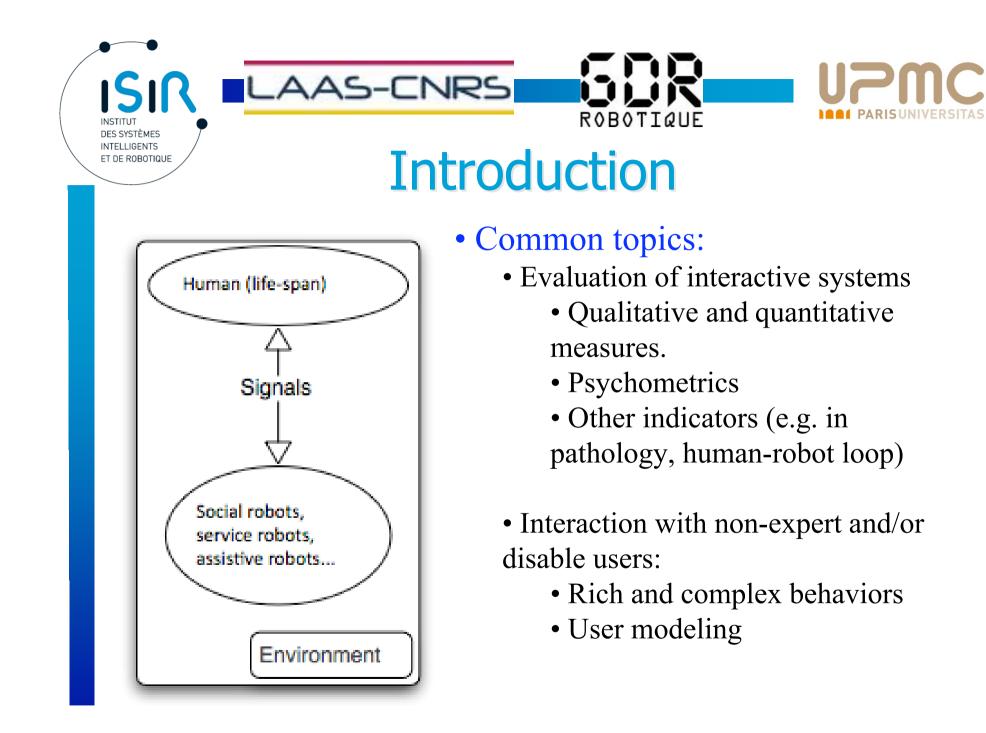
Mohamed.Chetouani@upmc.fr













Communicative signals

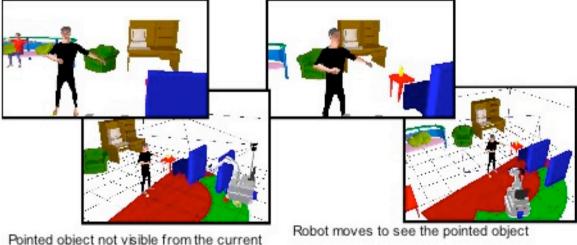
- Multi-modal perception of signals:
 - Robust methods suitable for mobility
 - Human centered design (movement, social signals, cognition/emotion...).
- Generation of communicative signals:
 - Virtual reality, expressiveness
- Social Psychology in HRI:
 - Relevant and natural scenarios/situations
 - Acceptability
 - Metrics...



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- Efficient communication (dialogue, intentions...)
- Planning and control of complex tasks with an explicit closed loops
- Learning techniques for context modeling: human, various situations, environment...
- Safety...

DES SYSTÈMES INTELLIGENTS ET DE ROBOTIQUE



Robot configuation

Ubiquitous Networked Robots

ROBOTTOLIF

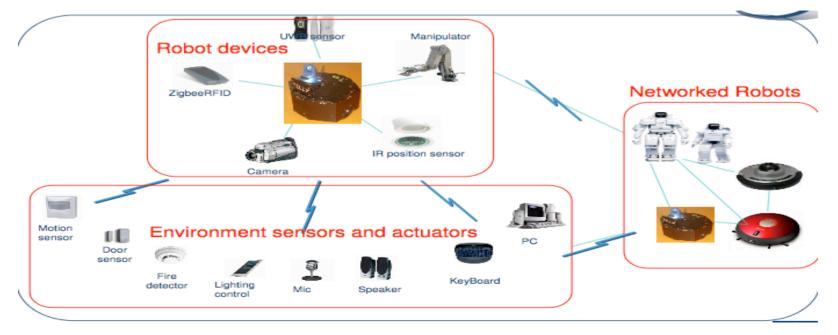
Ambient intelligence and ubiquitous approaches:

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Multiple sensors and robots...

DES SYSTÈMES INTELLIGENTS ET DE ROBOTIQUE

- Open environment, partially known and dynamic.
- Inter-operability with humans, communicative objects and robots.



Summary

Topics

ET DE ROBOTIQUE

- Perception, interpretation, prediction and synthesis of communicative signals.
- Decision, planning, control of proactive and/or reactive behaviors for allowing the robot to achieve complex tasks and learn to cooperate with humans.
- Multi-robots interaction

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- Interdisciplinary approach:
 - « Virtual human and humanoids »: ECA, mixed worlds.
 - Social psychology for HRI: acceptability, ethics, cognitive interaction, assistive robotics (pathology), planning tasks...

